## GE Energy



## RCS* Actuators

Versatile Automation Solutions
go imagination at work

Electric Actuators
Overview/Features \& Benefits. $\qquad$ 3-4
MAR/DCR-10, 50 \& 90 $\qquad$ 5-7
Outline Dimensions (MAR/DCR-10, 50 \& 90 ) $\qquad$ 6
Selection Charts $\qquad$ 7-8
MAR/DCR-100, 120, 160, 250, 800, 1600 \& 4000. $\qquad$ 9-16
Outline Dimensions (MAR/DCR-100, 120, 160 \& 250) $\qquad$ 10
Outline Dimensions (MAR/DCR-800) $\qquad$ 11
Outline Dimensions (MAR 1600-70, 4000-125, 4000-170) $\qquad$ 12-13
Selection Charts $\qquad$ 14-16
SURE 24/25, 49, 100, 150. $\qquad$ 17-25
Outline Dimensions (SURE 24/25) $\qquad$ 18
Outline Dimensions (SURE 49). $\qquad$ 20
Outline Dimensions (SURE 100) $\qquad$ 22
Outline Dimensions (SURE 150) $\qquad$ 24
Selection Charts $\qquad$ 25
CONTROLS
EASC SCC-10 (Micro-Processor Based Analog Controller). $\qquad$ 26-27
DPC-100 \& DPC-120 (Profibus ${ }^{\circledR}$ DP Actuator Controller) $\qquad$ 28
DNET115 (DeviceNet™ Actuator Controller) $\qquad$ 29
ModBus Actuator Controller. $\qquad$ 30

## RCS Actuators from GE Energy: Exceptional Automation Solutions

RCS actuator products from GE Energy offer exceptional automation solutions for valve and equipment manufacturers and end users in the commercial, industrial, marine and power industries.

Applicable to a myriad of automation solutions, from simple on/off control to heavy modulating, RCS actuators have been used in a variety of challenging, dirty and hazardous environments. GE specializes in offering engineered actuator solutions for your unique or unusual applications.

## Versatile, Advanced Technology Electric Rotary Actuators

Our electric rotary line offers a broad range of highly versatile actuator products. Targeted to $1 / 4$ turn and multi-turn valves and dampers, RCS electric rotary actuators are also well suited for use in the automation of other types of rotating equipment.
These rotary models span a torque range of 120 to 48,000 inch pounds with stroke speeds for $1 / 4$ turn valves ranging from 0.5 seconds to 3 minutes and for multi-turn actuators from 7.5 to 30 rpm .

## Cost-effective, Low-maintenance Spring Return Actuators

Our spring return electric rotary actuators employ torsion power springs that provide a reliable mechanical actuation solution for emergency shutoff or shutdown situations. This approach offers a cost-effective, low-maintenance and superior alternative to pneumatic, hydraulic, electrohydraulic or battery backup systems.
The spring return electric rotary actuators have spring-ending torque to 1,800 inch pounds and are also available with speed options for simple on/off or modulating applications. Clockwise and counter-clockwise spring return options are available to drive any $1 / 4$ turn device to a fail position upon loss of power.

## An Extensive Array of the Latest Control Solutions

GE offers an extensive line of electrical and electronic accessories for RCS actuators, including the latest solutions to industry demands for analog control plus communication bus capabilities, including the protocols supported are Profibus* DP, DeviceNet*, and Modbus*.

## Features \& Benefits

Application Flexibility. RCS actuators from GE Energy offers a broad and diverse range of speeds and available voltages. Coupled with an extensive line of control and communication accessories, these actuators offer both standard and unique solutions to a host of automation requirements. Standard operation for MAR and DCR models is part turn, reversible with unidirectional and multi-turn options available.
Electric Motors. All RCS electric actuators are powered by an extended duty, high-torque, reversible motor. These motors are suitable for both on/off and modulating applications, with many models rated for extended duty. Each motor is Class " B " insulated and has an internal thermal overload protective device. This device protects the motor if a "stall" condition occurs thus preventing the motor from overheating which results in premature motor failure.
Precision Gearing. All gears used in RCS actuators are manufactured from high alloy steel. Each gear is precision machined, then heat-treated, giving the gears exceptional strength. Each gear assembly is designed and tested to withstand the stall torque generated by the motor.
Permanent Lubrication. Each gear and spring assembly is permanently lubricated with a high quality lubricant selected to meet a wide range of operational and environmental conditions. Periodic lubrication is not required.
Versatile Installation. All RCS actuators can be installed and operated in any position. This allows flexibility for installation in confined locations or in retrofit applications.
Manual Override. MAR/DCR10, 50 and 90 models feature a declutchable manual override. The actuator gearing is disengaged from the motor thus the actuator cannot be operated electrically while in manual operation. MAR100 through 4000 feature a manual override with an automatic electrical safety lockout switch. When the handwheel is engaged, the electrical switch isolates the motor from the supply voltage to prevent electrical operation.

Environmental. With electroless nickel plated output shafts and stainless steel external bolting, RCS actuators will stand up to a broad range of environmental conditions. Optional marine epoxy paint systems or electroless nickel plated enclosures are also available to meet most onshore or offshore conditions.
Standard Coating System. Electrostatically applied powder coating
Optional Coating System. Ameron 2 part, water based epoxy, Sherwin Williams KEM Aqua ${ }^{\circ} 280$ Water Reducible Enamel, or Electroless Nickel Plating
Position Indication. Mechanical position indicators are standard on every model. These devices provide an external position reference for the actuator or driven equipment.
Simple and Easy Wiring. Every actuator has a clearly marked and accessible terminal strip to provide for quick termination of field wiring.

## Accessories.

- Integral potentiometer
- Auxiliary limit switches
- Interposing relays
- Motor brakes
- D.C. analog position transmitter with integral power supply
- D.C. analog position (loop powered)
- D.C. analog position controller
- Digi-Tork bi-directional torque control
- Digi-Speed variable speed control
- Communication bus interface:
- Profibus DP
- DeviceNet"
- Modbus


## Part-Turn Electric | Multi-Turn Electric

Optional 7" Handwheel Available


| NEMA 4 Enclosure |
| :--- |
| Approvals |
| MAR Models Only |
| (Canadian Standard Association) |
| CSA NRTL/C - Enclosure |



| NEMA 7 Enclosure |  |
| :--- | :--- |
| Approvals |  |
| MAR Models Only |  |
| (Canadian Standard Association) |  |
| CSA NRTL/C | Class I, Divisions $1 \& 2$, <br> Groups C \& D |
| CSA NRTL/C | Class II, Divisions $1 \& 2$, <br> Groups E, F, \& G |
| CSA NRTL/C | Approved to UL Standard No. <br> 429, Electrically Operated |
| Values |  |


| Models |
| :---: |
| MAR10, 50, 90 - A.C. Supply DCR10, 50, 90 - D.C. Supply |
| Typical Application |
| For on/off and modulating control of: <br> - Part turn ball, butterfly or plug valves <br> - Rotary dampers <br> - Rotating equipment <br> - Multi-turn valve types |
| Temperature Range |
| $\begin{array}{r} \text { Standard: }-40^{\circ} \mathrm{F} \text { to }+150^{\circ} \mathrm{F} \\ -40^{\circ} \mathrm{C} \text { to }+66^{\circ} \mathrm{C} \end{array}$ |
| Optional: $\begin{aligned} &-60^{\circ} \mathrm{F} \text { to }+120^{\circ} \mathrm{F} \\ &-51^{\circ} \mathrm{C} \text { to }+49^{\circ} \mathrm{C}\end{aligned}$ |
| (Note: With Heaters Installed) |
| Optional: Compliance to NFPA 130, capable of operation after exposure to ambient temperature of $482^{\circ} \mathrm{F}\left(250^{\circ} \mathrm{C}\right)$ for a minimum of 1 hour |
| Voltage |
| 115 VAC, 1 Phase, 50/60 Hz. 230 VAC, 1 Phase, $50 / 60 \mathrm{~Hz}$. 24 VAC, 1 Phase, 50/60 Hz. 12 VDC / 24 VDC |
| Torque Range |
| 30 to 1,000 inch pounds (3.4 to 113.0 newton meters) |
| Speed Range |
| For 60 Hz . operation: .6 to 60 seconds for $90^{\circ}$ revolution .3 and 30 RPM for multi-turns |
| Standard Features |
| AC Voltages <br> 2 - SPDT Switches, PTC Heater DC Voltages 2 - SPDT (High Current) Switches |



Modulating


Multi-Turn

## Part-Turn Electric | Multi-Turn Electric

Outline Dimensions (Inches) - MAR \& DCR 10, 50, \& 90

| Weight |
| :--- |
| NEMA 4 Enclosure: $12 \mathrm{lbs} . / 5.4 \mathrm{~kg}$ |
| NEMA 7 Enclosure: $16 \mathrm{lbs} . / 7.3 \mathrm{~kg}$ |



## Mounting Geometry - Bottom View



## Notes

1. Direction of rotation is based on viewing actuator from top.
2. Drawing shows output shaft in a fully clockwise (closed) position.
3. Actuator shown with indicator in electrical mode.
4. A NEMA 4 control enclosure is shown. Dimensions given are accurate for NEMA 7 .

## Part-Turn Electric | Multi-Turn Electric

115 \& 230 VAC, 1 Phase, $50 / 60 \mathrm{~Hz}$.

| Model | Output Torque Inch Pounds (N.m) | Type | Speed of Operation 60 Hz . $(50 \mathrm{~Hz}$.) | Duty Cycle Rating 115 Vac, 1 Ph., $50 / 60 \mathrm{~Hz}$. | Duty Cycle Rating 230 Vac, 1Ph., $50 / 60 \mathrm{~Hz}$. | Current Ratings 115 VAC |  | Current Ratings 230 VAC |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | NLA* | LRA* | NLA* | LRA* |
| MAR 10-.5MT | 30 (3.4) | Multi-Turn | 30 RPM N/A | $\begin{gathered} 25 \% \\ \text { (2) } \end{gathered}$ | $\begin{gathered} 25 \% \\ (2) \end{gathered}$ | 0.50 | 0.82 | 0.25 | 0.40 |
| MAR 10-2 | 120 (13.6) | Part Turn | $\begin{gathered} 2 \text { second } / 90^{\circ} \\ \left(2.5 \text { seconds } / 90^{\circ}\right) \end{gathered}$ | $\begin{gathered} 50 \% \\ (1) \end{gathered}$ | $\begin{gathered} 50 \% \\ (1) \end{gathered}$ | 0.40 | 0.60 | 0.30 | 0.40 |
| MAR 10-2MT | 120 (13.6) | Multi-Turn | $\begin{aligned} & 7.5 \mathrm{RPM} \\ & \text { (6.2 RPM) } \end{aligned}$ | $50 \%$ (2) | $\begin{gathered} 50 \% \\ (2) \end{gathered}$ | 0.40 | 0.60 | 0.20 | 0.25 |
| MAR 10-10 | 350 (39.5) | Part Turn | 10 seconds $/ 90^{\circ}$ <br> (12 seconds/90 ) | $\begin{gathered} 50 \% \\ (1) \end{gathered}$ | $\begin{gathered} 50 \% \\ (1) \end{gathered}$ | 0.40 | 0.60 | 0.20 | 0.25 |
| MAR 10-30 | 425 (48.0) | Part Turn | 30 seconds $/ 90^{\circ}$ <br> ( 35 seconds $/ 90^{\circ}$ ) | $50 \%$ <br> (2) | $50 \%$ <br> (2) | 0.30 | 0.50 | 0.20 | 0.25 |
| MAR 10-60 | 400 (45.2) | Part Turn | 60 seconds $/ 90^{\circ}$ <br> (70 seconds/ $90^{\circ}$ ) | $\begin{gathered} 50 \% \\ (2) \end{gathered}$ | $50 \%$ (2) | 0.35 | 0.55 | 0.20 | 0.25 |
| MAR 50-.5MT | 200 (22.6) | Multi-Turn | $\begin{gathered} 30 \text { RPM } \\ \text { N/A } \end{gathered}$ | $25 \%$ <br> (2) | - | 1.90 | 3.10 | - | - |
| MAR 50-2 | 600 (67.8) | Part Turn | $\begin{gathered} 2 \text { seconds } / 90^{\circ} \\ \left(2.5 \text { seconds } / 90^{\circ}\right) \end{gathered}$ | $40 \%$ (1) | $\begin{gathered} 50 \% \\ (1) \end{gathered}$ | 1.60 | 2.20 | 0.50 | 0.95 |
| MAR 50-2MT | 600 (67.8) | Multi-Turn | $\begin{aligned} & 7.5 \mathrm{RPM} \\ & \text { (6.2 RPM) } \end{aligned}$ | 40\% (2) | $50 \%$ (2) | 1.60 | 2.20 | 0.50 | 0.95 |
| MAR 50-10 | 600 (67.8) | Part Turn | 10 seconds $/ 90^{\circ}$ <br> (12 seconds/ $90^{\circ}$ ) | $\begin{gathered} 50 \% \\ (1) \end{gathered}$ | $\begin{gathered} 50 \% \\ (1) \end{gathered}$ | 0.50 | 0.80 | 0.30 | 0.50 |
| MAR 50-30 | 700 (79.1) | Part Turn | 30 seconds $/ 90^{\circ}$ <br> (35 seconds/ $90^{\circ}$ ) | $50 \%$ <br> (2) | $50 \%$ <br> (2) | 0.35 | 0.55 | 0.20 | 0.25 |
| MAR 50-60 | 600 (67.8) | Part Turn | 60 seconds $/ 90^{\circ}$ <br> (70 seconds/ $90^{\circ}$ ) | $50 \%$ (2) | $50 \%$ (2) | 0.30 | 1.50 | 0.20 | 0.25 |
| MAR 90-5 | 1,000 (113.0) | Part Turn | 5 seconds $/ 90^{\circ}$ <br> ( 6 seconds $/ 90^{\circ}$ ) | $\begin{gathered} 50 \% \\ (1) \end{gathered}$ | $\begin{gathered} 50 \% \\ (1) \end{gathered}$ | 0.55 | 1.55 | 0.25 | 0.85 |
| MAR 90-5MT | 1,000 (113.0) | Multi-Turn | $\begin{gathered} 3 \mathrm{RPM} \\ \text { (2.5 RPM) } \end{gathered}$ | $50 \%$ <br> (2) | $50 \%$ <br> (2) | 0.55 | 1.55 | 0.25 | 0.85 |
| MAR 90-15 | 1,000 (113.0) | Part Turn | 15 seconds $/ 90^{\circ}$ (17.5 seconds/90 $)$ | $75 \%$ <br> (2) | $50 \%$ <br> (2) | 0.50 | 0.60 | 0.20 | 0.35 |
| ( (N.L.A.) - No Load | ad Ampere | (L.R.A.) - Locked Rotor Ampere |  | (1) - Open/Close Service |  | n/Close | dulatin |  |  |

## Duty Cycle

The percentage of time the electric motor is energized vs. the time it is at rest, in reversing duty and with the actuator running at it's rated load maximum published torque.

## Standard Modulating Duty Rating

- 12 motor starts (corrections) per minute
- At the rated duty cycle for that model
- With the speed of operation a minimum of 15 seconds for $90^{\circ}$ or slower
- With positioning accuracy of (+/-) $1 \%$ of total span


## Isolation Relays

To operate multiple actuators in parallel from a single signal requires isolating relays in the field wiring. Consult factory.

Note - Multi-turn models are available with the following number of turns:
$1.4,5,8,13,18,26$ or 50 . Must be specified when the order is placed.

## Part-Turn Electric | Multi-Turn Electric

24 VAC

| Model | Output Torque Inch Pounds (N.m) | Type | Speed of Operation 60 Hz . 50 Hz .) | Duty Cycle Rating 24 VAC | Current Ratings 24 VAC |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | NLA* | LRA* |
| MAR 10-2 | 120 (13.6) | Part Turn | 2 seconds/90 ${ }^{\circ}$ | 25\% (1) | 2.80 | 3.50 |
| MAR 10-2MT | 120 (13.6) | Multi-Turn | 7.5 RPM | 25\% (1) | 2.80 | 3.50 |
| MAR 10-10 | 350 (39.5) | Part Turn | 10 seconds/ $90^{\circ}$ | 25\% (1) | 1.90 | 2.70 |
| MAR 10-30 | 425 (48.0) | Part Turn | 30 seconds $/ 90^{\circ}$ | 25\% (1) | 1.70 | 2.40 |
| MAR 10-60 | 400 (45.2) | Part Turn | 60 seconds/90 ${ }^{\circ}$ | 25\% (1) | 1.80 | 2.50 |
| MAR 50-10 | 600 (67.8) | Part Turn | 10 seconds/90 | 25\% (1) | 3.80 | 4.70 |
| MAR 50-30 | 700 (79.1) | Part Turn | 30 seconds/ $90^{\circ}$ | 25\% (1) | 1.90 | 2.70 |
| MAR 90-15 | 1,000 (113.0) | Part Turn | 15 seconds $/ 90^{\circ}$ | 25\% (1) | 2.40 | 4.00 |

12 \& 24 VDC

| Model | Output Torque Inch Pounds (N.m) | Type | No Load Speed of Operation | Duty Cycle Rating 12 VDC | Duty Cycle Rating 24 VDC | Current Ratings 12 VAC |  | Current Ratings 24 VAC |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | NLA* | LRA* | NLA* | LRA* |
| DCR 10-2 | 250 (28.2) | Part Turn | . 6 seconds/90 ${ }^{\circ}$ | 50\% (1) | 50\% (1) | 1.00 | 12.5 | 0.75 | 6.80 |
| DCR 10-2MT | 250 (28.2) | Multi-Turn | 25 RPM | 50\% (2) | 50\% (2) | 1.00 | 12.5 | 0.75 | 6.80 |
| DCR 10-10 | 400 (45.2) | Part Turn | 6.4 seconds/ $90^{\circ}$ | 50\% (1) | 50\% (1) | 0.19 | 3.90 | 0.08 | 2.10 |
| DCR 50-2 | 600 (67.8) | Part Turn | . 7 seconds/90 | 50\% (1) | 50\% (1) | 1.00 | 22.00 | 0.75 | 12.00 |
| DCR 50-2MT | 600 (67.8) | Multi-Turn | 21 RPM | 50\% (2) | 50\% (2) | 1.00 | 22.00 | 0.75 | 12.00 |
| DCR 50-10 | 600 (67.8) | Part Turn | 5.6 seconds/ $90^{\circ}$ | 50\% (1) | 50\% (1) | 0.90 | 5.80 | 0.5 | 2.40 |
| DCR 50-30 | 700 (79.1) | Part Turn | 21 seconds/90 ${ }^{\circ}$ | 50\% (2) | 50\% (2) | 0.15 | 2.65 | 0.06 | 1.15 |
| DCR 90-5 | 900 (101.7) | Part Turn | 2.2 seconds $/ 90^{\circ}$ | 50\% (1) | 50\% (1) | 1.00 | 12.50 | 0.75 | 6.80 |
| DCR 90-5MT | 900 (101.7) | Multi-Turn | 7 RPM | 50\% (2) | 50\% (2) | 1.00 | 12.50 | 0.75 | 6.80 |
| DCR 90-15 | 900 (101.7) | Part Turn | 5.6 seconds/90 ${ }^{\circ}$ | 50\% (2) | 50\% (2) | 0.90 | 5.80 | 0.50 | 2.40 |

* (N.L.A.) - No Load Ampere (L.R.A.) - Locked Rotor Ampere (1) - Open/Close Service (2) - Open/Close or Modulating Service


## Limit Switches (MAR Models)

Standard: Two-single pole, double throw type (SPDT) with an option for 2 or 4 additional.
Ratings: UL and CSA listed.
15 amp \& $1 / 2$ H.P. at 125 or 250 VAC ; $1 / 2$ amp at 125 VDC ;
$1 / 4 \mathrm{amp}$ at $250 \mathrm{VDC} ; 5 \mathrm{amp}$ at 120 VAC
Optional: All double pole, double throw type (DPDT).
Ratings: UL and CSA listed.
10 amp at $125 / 250 \mathrm{VAC}$ (form ZZ);
$1 / 2$ H.P. at 125 VDC; $3 / 4$ H.P. at 250 VAC

## Limit Switches (DCR Models)

Ratings: Ratings: UL and CSA listed.
MIL-PRF-8805 Qualified Listing 25 amp at $277 \mathrm{VAC} ; 1$ H.P. at 125 VAC ;
2 H.P. at 250 VAC

## Isolation Relays

To operate multiple actuators in parallel from a single signal requires isolating relays in the field wiring. Consult factory.
Note - Multi-turn models are available with the following number of turns: $1.4,5,8,13,18,26$ or 50 . Must be specified when the order is placed.

## Part-Turn Electric | Multi-Turn Electric



| Approvals |  |
| :--- | :--- |
| NEMA 4/6/7 Enclosure |  |
| MAR Models Only |  |
| (Canadian Standard Association) |  |


| Models |  |
| :---: | :---: |
| A.C. Voltage | D.C. Voltage |
| MAR100 <br> MAR120 <br> MAR160 <br> MAR250 <br> MAR800 | $\begin{aligned} & \text { DCR100 } \\ & \text { DCR160 } \\ & \text { DCR250 } \\ & \text { DCR800 } \end{aligned}$ |
| Typical Application |  |
| For on/off and modulating control of: <br> - Part turn ball, butterfly or plug valves <br> - Multi-turn valve types <br> - Rotary dampers <br> - Rotating equipment |  |
| Temperature Range |  |
| $\begin{array}{r} \text { Standard: }-40^{\circ} \mathrm{F} \text { to }+150^{\circ} \mathrm{F} \\ -40^{\circ} \mathrm{C} \text { to }+66^{\circ} \mathrm{C} \end{array}$ |  |
| $\begin{aligned} \text { Optional: } & -60^{\circ} \mathrm{F} \text { to }+120^{\circ} \mathrm{F} \\ & -51^{\circ} \mathrm{C} \text { to }+49^{\circ} \mathrm{C} \end{aligned}$ |  |
| (Note: With Heaters Installed) |  |
| Optional: Compliance to NFPA 130, capable of operation after exposure to ambient temperature of $482^{\circ} \mathrm{F}$ $\left(250^{\circ} \mathrm{C}\right)$ for a minimum of 1 hour |  |
| Voltage |  |
| 115 VAC, 1 Phase, 50/60 Hz. 230 VAC, 1 Phase, 50/60 Hz. $24 \mathrm{VAC}, 1$ Phase, $50 / 60 \mathrm{~Hz}$. 220 VAC, 3 Phase, 60 Hz . 440 VAC, 3 Phase 60 Hz . 12 VDC 24 VDC |  |
| Torque Range |  |
| 1,500 to 10,000 inch pounds (169.5 to 1129.8 newton meters) |  |
| Speed Range |  |
| For 60 Hz . operation: <br> 1.25 to 60 seconds for $90^{\circ}$ revolution <br> 5 and 12 RPM for multi-turns |  |
| Standard Features |  |
| AC (Single and Three Phase ) Voltages 4 - SPDT Switches, PTC Heater DC Voltages 4 - SPDT (High Current) Switches |  |



## Part-Turn Electric | Multi-Turn Electric

Outline Dimensions (Inches) - MAR \& DCR 100, 120, 160 \& 250



## Mounting Geometry



## Notes

1. Drawing shows the actuator output shaft in a fully clockwise (closed) position.
2. Direction of actuator rotation is based on the top view from the handwheel.
3. A NEMA 4 control cover is shown.

Dimensions given are accurate for NEMA 4/6/7.
4. Actuator is shown with handwheel in auto position. Height is $13.0^{\prime \prime}$ when manual override is used.

## Part-Turn Electric | Multi-Turn Electric

Outline Dimensions (Inches) - MAR \& DCR 800

| Weight |
| :--- |
| NEMA 4 Enclosure: $34 \mathrm{lbs} / 15.4 \mathrm{~kg}$ |
| NEMA $4 / 6 / 7$ Enclosure: $44 \mathrm{lbs} / 20 \mathrm{~kg}$ |



## Mounting Geometry



## Notes

1. Drawing shows the actuator output shaft in a fully clockwise (closed) position.
2. Direction of actuator rotation is based on the top view from the handwheel.
3. A NEMA 4 control cover is shown.

Dimensions given are accurate for NEMA 4/6/7.
Actuator is shown with handwheel in auto position. Height is $13.3^{\prime \prime}$ when manual override is used.

## Part-Turn Electric



## NEMA 4/6/7 Enclosure

Approvals

| A.C. Models Only <br> (Canadian Standard Association) |  |
| :--- | :--- |
| CSA NRTL/C | Type 4 and 6 | CSA NRTL/C | Class I, Divisions $1 \& 2$, Groups |
| :--- | :--- |
| C \& D |$|$

CSA NRTL/C Approved to UL Standard No. 1203, Electrical Equipment for use in Explosion - proof And Dust - Ignition - proof Hazardous (Classified) Locations

## Part-Turn Electric

Outline Dimensions (Inches) - MAR 1600-70 and 4000-170


- $\begin{aligned} & 10.0 \text { Clearance } \\ & \text { for cover removal }\end{aligned}$


Mounting Geometry


## Notes

1. Drawing shows the actuator output shaft in a fully clockwise (closed) position.

Direction of actuator rotation is based on the top view of the eternal gearbox.
Actuator is shown with handwheel in auto position.
Height is $2.4^{\prime \prime}$ when manual override is used.

## Part-Turn Electric | Multi-Turn Electric

115 \& 230 VAC, 1 Phase, $50 / 60 \mathrm{~Hz}$.

| Model | Output <br> Torque Inch Pounds (N.m) | Type | $\begin{aligned} & \text { Speed of Operation } \\ & 60 \mathrm{~Hz} \text {. }(50 \mathrm{~Hz} .) \end{aligned}$ | Duty Cycle Rating 115 Vac, 1Ph., $50 / 60 \mathrm{~Hz}$. | $\begin{gathered} \text { Duty Cycle } \\ \text { Rating } \\ 230 \mathrm{VaC} \text {, } \\ 1 \mathrm{Ph}, 50 / 60 \\ \mathrm{~Hz} . \end{gathered}$ | Current Ratings 115 VAC |  | Current Ratings 230 VAC |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | NLA* | LRA* | NLA* | LRA* |
| MAR 100-16 | 1,500 (169) | Part Turn | 16 seconds $/ 90^{\circ}$ <br> (19 seconds/90 ${ }^{\circ}$ ) | $\underset{(2)}{100 \%}$ | $\begin{gathered} 50 \% \\ (2) \end{gathered}$ | 0.55 | 1.55 | 0.25 | 0.85 |
| MAR 100-30 | 1,800 (203) | Part Turn | 30 seconds $/ 90^{\circ}$ <br> (35 seconds $/ 90^{\circ}$ ) | $\begin{gathered} 100 \% \\ (2) \end{gathered}$ | $\begin{gathered} 50 \% \\ (2) \end{gathered}$ | 0.50 | 0.60 | 0.30 | 0.35 |
| MAR 100-60 | 2500 (282) | Part Turn | 60 seconds $/ 90^{\circ}$ <br> (70 seconds/90 $)$ | $\underset{(2)}{100 \%}$ | $\begin{gathered} 50 \% \\ (2) \end{gathered}$ | 0.35 | 0.55 | 0.20 | 0.35 |
| MAR 120-1.25 | 1,500 (169) | Part Turn | 1.25 seconds $/ 90^{\circ}$ $\left(2\right.$ seconds $\left./ 90^{\circ}\right)$ | $\underset{\text { 25\% }}{\substack{111}}$ | $\underset{(1)}{25 \%}$ | 3.30 | 7.40 | 1.30 | 3.60 |
| MAR 120-1.25 MT | 1,500 (169) | Multi- <br> Turn | 12 RPM (10 RPM) | $\begin{aligned} & 25 \% \\ & \text { (2) } \end{aligned}$ | $\begin{aligned} & 25 \% \\ & \text { (2) } \end{aligned}$ | 3.30 | 7.40 | 1.30 | 3.60 |
| MAR 160-8 | 1,920 (217) | Part Turn | 8 seconds $/ 90^{\circ}$ <br> ( 9 seconds $/ 90^{\circ}$ ) | $\begin{gathered} 50 \% \\ (1) \end{gathered}$ | $50 \%$ | 0.75 | 1.65 | 0.70 | 1.05 |
| MAR 160-16 | 2,000 (226) | Part Turn | $\begin{aligned} & 16 \text { seconds } / 90^{\circ} \\ & \left(19 \text { seconds } / 90^{\circ}\right. \text { ) } \end{aligned}$ | $\begin{aligned} & 75 \% \\ & \text { (2) } \end{aligned}$ | $\begin{aligned} & 50 \% \\ & (2) \end{aligned}$ | 0.60 | 1.60 | 0.35 | 0.90 |
| MAR 160-30 | 2,500 (282) | Part Turn | 30 seconds $/ 90^{\circ}$ <br> (35 seconds/ $90^{\circ}$ ) | $\begin{gathered} 75 \% \\ (2) \end{gathered}$ | $\begin{gathered} 50 \% \\ (2) \end{gathered}$ | 0.65 | 0.70 | 0.45 | 0.50 |
| MAR 160-60 | 2,800 (316) | Part Turn | 60 seconds $/ 90^{\circ}$ <br> (70 seconds/ $90^{\circ}$ ) | $\begin{gathered} 100 \% \\ (2) \end{gathered}$ | $\begin{aligned} & 50 \% \\ & (2) \end{aligned}$ | 0.50 | 0.60 | 0.30 | 0.35 |
| MAR 250-3 | 3,500 (395) | Part Turn | 3 seconds $/ 90^{\circ}$ <br> ( 4 seconds $/ 90^{\circ}$ ) | 25\% | $\begin{gathered} 50 \% \\ (1) \end{gathered}$ | 3.30 | 7.40 | 0.90 | 3.40 |
| MAR 250-3MT | 3,500 (395) | Multi- <br> Turn | 5 RPM (4 RPM) | $\begin{aligned} & 25 \% \\ & (2) \end{aligned}$ | $\begin{aligned} & 50 \% \\ & \text { (2) } \end{aligned}$ | 3.30 | 7.40 | 0.90 | 3.40 |
| MAR 250-8 | 3,000 (339) | Part Turn | 8 seconds $/ 90^{\circ}$ <br> (9 seconds/90 ) | 40\% | $\begin{aligned} & 50 \% \\ & (1) \end{aligned}$ | 1.60 | 2.20 | 1.00 | 1.25 |
| MAR 250-16 | 4,000 (452) | Part Turn | 16 seconds/90 ${ }^{\circ}$ <br> (19 seconds/90 ${ }^{\circ}$ ) | $\begin{gathered} 50 \% \\ (2) \end{gathered}$ | $\begin{gathered} 50 \% \\ (2) \end{gathered}$ | 1.10 | 1.80 | 0.70 | 1.05 |
| MAR 250-30 | 5,000 (565) | Part Turn | 30 seconds $/ 90^{\circ}$ <br> (35 seconds/ $90^{\circ}$ ) | $\begin{gathered} 50 \% \\ (2) \end{gathered}$ | $\begin{gathered} 50 \% \\ (2) \end{gathered}$ | 0.75 | 1.65 | 0.50 | 0.95 |
| MAR 250-60 | 5,000 (565) | Part Turn | 60 seconds $/ 90^{\circ}$ <br> 170 seconds $/ 90^{\circ}$ | $\begin{gathered} 75 \% \\ (2) \end{gathered}$ | $\begin{gathered} 50 \% \\ (2) \end{gathered}$ | 0.65 | 0.70 | 0.30 | 0.35 |
| MAR 800-12 | 7,500 (847) | Part Turn | 12 seconds/90 <br> (14 seconds/90 ${ }^{\circ}$ ) | $\begin{gathered} 25 \% \\ (1) \end{gathered}$ | $\begin{gathered} 25 \% \\ (1) \end{gathered}$ | 3.30 | 7.40 | 0.90 | 3.40 |
| MAR8 00-30 | $\begin{aligned} & 10,000 \\ & (1,130) \end{aligned}$ | Part Turn | 30 seconds $/ 90^{\circ}$ <br> (35 seconds/ $90^{\circ}$ ) | $\begin{gathered} \text { 40\% } \\ \text { (2) } \end{gathered}$ | $\begin{gathered} 50 \% \\ (2) \end{gathered}$ | 1.60 | 2.20 | 1.00 | 1.20 |
| MAR 800-60 | $\begin{aligned} & 10,000 \\ & (1,130) \end{aligned}$ | Part Turn | $\begin{aligned} & 60 \text { seconds } / 90^{\circ} \\ & \left(70 \text { seconds } / 90^{\circ}\right. \text { ) } \end{aligned}$ | $\begin{aligned} & 75 \% \\ & \text { (2) } \end{aligned}$ | $\begin{aligned} & 50 \% \\ & \text { (2) } \end{aligned}$ | 0.55 | 1.55 | 0.50 | 0.95 |
| MAR 1600-70 | $\begin{aligned} & 21,000 \\ & (2,373) \end{aligned}$ | Part Turn | 70 seconds $/ 90^{\circ}$ <br> ( 82 seconds $/ 90^{\circ}$ ) | $\begin{gathered} 25 \% \\ \text { (2) } \end{gathered}$ | $\begin{gathered} 50 \% \\ (2) \end{gathered}$ | 3.30 | 7.40 | 0.90 | 3.40 |
| MAR 4000-170 | $\begin{aligned} & 48,000 \\ & (5,424) \end{aligned}$ | Part Turn | 170 seconds $/ 90^{\circ}$ <br> ( 200 seconds $/ 90^{\circ}$ ) | $\begin{aligned} & 25 \% \\ & \text { (2) } \end{aligned}$ | $\begin{aligned} & 50 \% \\ & (2) \end{aligned}$ | 3.30 | 7.40 | 0.90 | 3.40 |

* (N.L.A.) - No Load Ampere (L.R.A.) - Locked Rotor Ampere (1) - Open/Close Service (2) - Open/Close or Modulating Service


## Duty Cycle

The percentage of time the electric motor is energized vs. the time it is at rest, in reversing duty and with the actuator running at it's rated load maximum published torque.

## Standard Modulating Duty Rating

- 12 motor starts (corrections) per minute.
- At the rated duty cycle for that model
- With the speed of operation a minimum of 15 seconds for $90^{\circ}$ or slower
- With positioning accuracy of (+/-) 1\% of total span


## Isolation Relays

To operate multiple actuators in parallel from a single signal requires isolating relays in the field wiring. Consult factory.

Note - Multi-turn models are available with the following number of turns: $1.4,5,8,13,18,26$ or 50. Must be specified when the order is placed.

## Part-Turn Electric | Multi-Turn Electric

## 12 \& 24 VDC

| Model | Output Torque Inch Pounds (N.m) | Type | No Load Speed of Operation | Duty Cycle Rating 12 VDC | $\begin{aligned} & \text { Duty Cycle } \\ & \text { Rating } \\ & 24 \text { VDC } \end{aligned}$ | Current Ratings 12 VAC |  | Current Ratings 24 VAC |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | NLA* | LRA* | NLA* | LRA* |
| DCR 100-30 | 2,000 (225) | Part Turn | 11.5 seconds/90 ${ }^{\circ}$ | 50\% (2) | 50\% (2) | 0.90 | 5.80 | 0.50 | 6.80 |
| DCR 160-16 | 2,200 (248) | Part Turn | 5.5 seconds/ $90^{\circ}$ | 50\% (1) | 50\% (1) | 1.00 | 12.50 | 0.75 | 6.80 |
| DCR 160-60 | 3,600 (406) | Part Turn | 22 seconds/ $90^{\circ}$ | 50\% (2) | 50\% (2) | 0.90 | 5.80 | 0.50 | 2.10 |
| DCR 250-8 | 3,000 (339) | Part Turn | 3.2 seconds/ $/ 90^{\circ}$ | 50\% (1) | 50\% (1) | 1.00 | 22.00 | 0.75 | 12.00 |
| DCR 250-16 | 4,000 (452) | Part Turn | 5.7 seconds/ $90^{\circ}$ | 50\% (1) | 50\% (1) | 1.00 | 22.00 | 0.75 | 12.00 |
| DCR 250-30 | 5,000 (565) | Part Turn | 11.2 seconds/90 | 50\% (2) | 50\% (2) | 1.00 | 12.50 | 0.75 | 2.40 |
| DCR 800-30 | 10,000 (1,130) | Part Turn | 13.3 seconds/90 ${ }^{\circ}$ | 50\% (2) | 50\% (2) | 1.00 | 22.00 | 0.75 | 1.15 |
| DCR 800-60 | 10,000 (1,130) | Part Turn | 23 seconds/ $90^{\circ}$ | 50\% (2) | 50\% (2) | 1.00 | 12.50 | 0.75 | 1.15 |

24 VAC

| Model | Output Torque <br> Inch Pounds (N.m) | Type | Speed of Operation <br> 60 Hz ( 50 Hz ) $)$ | Duty Cycle <br> Rating <br> 24 VAC | Current Ratings <br> 24 VAC |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| MAR 100-16 | $1,500(169)$ | Part Turn | 16 seconds $/ 90^{\circ}$ <br> $\left(19\right.$ seconds $\left./ 90^{\circ}\right)$ | $50 \%(2)$ | 5.60 | 6.00 |
| MAR 100-30 | $1,800(203)$ | Part Turn | 30 seconds $/ 90^{\circ}$ <br> $\left(35\right.$ seconds $\left./ 90^{\circ}\right)$ | $75 \%(2)$ | 2.40 | 4.50 |
| MAR 100-60 | $2,500(282)$ | Part Turn | 60 seconds $/ 90^{\circ}$ <br> $\left(70\right.$ seconds $\left./ 90^{\circ}\right)$ | $100 \%(2)$ | 1.80 | 3.80 |
| MAR 160-30 | $2,500(282)$ | Part Turn | 30 seconds $/ 90^{\circ}$ <br> $\left(35\right.$ seconds $\left./ 90^{\circ}\right)$ | $75 \%(2)$ | 4.50 | 5.00 |
| MAR 160-60 | $2,800(316)$ | Part-Turn | 60 seconds $/ 90^{\circ}$ <br> $\left(70\right.$ seconds $\left./ 90^{\circ}\right)$ | $75 \%(2)$ | 2.40 | 4.50 |
| MAR 250-60 | $5,000(565)$ | Part Turn | 60 seconds $/ 90^{\circ}$ <br> $\left(70\right.$ seconds $\left./ 90^{\circ}\right)$ | $50 \%(2)$ | 4.50 | 5.00 |

* (N.L.A.) - No Load Ampere (L.R.A.) - Locked Rotor Ampere (1) - Open/Close Service (2) - Open/Close or Modulating Service


## Limit Switches (MAR Models)

Standard: Four-single pole, double throw type (SPDT) with an option for 2 additional.
Ratings: UL and CSA listed.
$15 \mathrm{amp} \& 1 / 2$ H.P. at 125 or 250 VAC
$1 / 2$ amp at 125 VDC;
$1 / 4 \mathrm{amp}$ at 250 VDC
Lamp Load: 5 amp at 120 VAC
Optional: All double pole, double throw type (DPDT).
Ratings: UL and CSA listed.
10 amp at 125/250 VAC (form ZZ);
1/2 H.P. at 125 VDC; $3 / 4$ H.P. at
250 VAC

Limit Switches (DCR Models)
Ratings: Ratings: UL and CSA listed.
MIL-PRF-8805 Qualified Listing 25 amp at 277 VAC; 1 H.P. at 125 VAC; 2 H.P. at 250 VAC

## Isolation Relays

To operate multiple actuators in parallel from a single signal requires isolating relays in the field wiring.
Consult factory.

## Heater

PTC (Positive Temperature Coefficient) Heater standard in an AC Voltage Models

## Part-Turn Electric | Multi-Turn Electric

220 \& 440 VAC, 3 Phase, 60 Hz.

| Model | Output Torque Inch Pounds (N.m) | Type | Speed of Operation 60 Hz . $(50 \mathrm{~Hz}$.) | Duty Cycle Rating 220 Vac, 3Ph., 60 Hz . | Duty Cycle Rating 440 Vac 3Ph., 60 Hz . | Current Ratings 220 VAC |  | Current Ratings 440 VAC |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | NLA* | LRA* | NLA* | LRA* |
| MAR 100-16 | 1,500 (169) | Part Turn | $\begin{gathered} 16 \text { seconds } / 90^{\circ} \\ \left(19 \text { seconds } / 90^{\circ}\right. \text { ) } \end{gathered}$ | 25\% | 25\% | 0.34 | 1.20 | 0.15 | 0.75 |
| MAR 120-1.25 | 1,500 (169) | Part Turn | 1.25 seconds $/ 90^{\circ}$ <br> (2 seconds/90 ) | 25\% | 25\% | 1.60 | 3.50 | 0.82 | 1.80 |
| $\begin{gathered} \text { MAR 120-1.25 } \\ \text { MT } \end{gathered}$ | 1,500 (169) | Multi-Turn | 12 RPM (10 RPM) | 25\% | 25\% | 1.60 | 3.50 | 0.82 | 1.80 |
| MAR 160-8 | 1,920 (217) | Part Turn | $\begin{gathered} 8 \text { seconds } / 90^{\circ} \\ \left(9 \text { seconds } / 90^{\circ}\right. \text { ) } \end{gathered}$ | 25\% | 25\% | 0.34 | 1.20 | 0.15 | 0.75 |
| MAR 160-16 | 2,000 (226) | Part Turn | $\begin{aligned} & 16 \text { seconds } / 90^{\circ} \\ & \left(19 \text { seconds } / 90^{\circ}\right. \text { ) } \end{aligned}$ | 25\% | 25\% | 0.34 | 1.20 | 0.15 | 0.75 |
| MAR 250-3 | 3,500 (316) | Part Turn | 3 seconds $/ 90^{\circ}$ <br> (4 seconds/90 ) | 25\% | 25\% | 1.60 | 3.50 | 0.82 | 1.80 |
| MAR 250-3MT | 3,500 (316) | Multi-Turn | 5 RPM (4 RPM) | 25\% | 25\% | 1.60 | 3.50 | 0.82 | 1.80 |
| MAR 250-16 | 4,000 (452) | Part Turn | $\begin{gathered} 16 \text { seconds } / 90^{\circ} \\ \left(19 \text { seconds } / 90^{\circ}\right. \text { ) } \end{gathered}$ | 25\% | 25\% | 0.34 | 1.20 | 0.15 | 0.75 |
| MAR 250-30 | 5,000 (565) | Part Turn | 30 seconds $/ 90^{\circ}$ <br> $\left(35\right.$ seconds $/ 90^{\circ}$ ) | 25\% | 25\% | 0.34 | 1.20 | 0.15 | 0.75 |
| MAR 250-60 | 5,000 (565) | Part Turn | $\begin{aligned} & 60 \text { seconds } / 90^{\circ} \\ & \left(70 \text { seconds } / 90^{\circ}\right) \end{aligned}$ | 25\% | 25\% | 0.34 | 1.20 | 0.15 | 0.75 |
| MAR 800-12 | 7,500 (847) | Part Turn | 12 seconds $/ 90^{\circ}$ <br> (14 seconds/ $90^{\circ}$ ) | 25\% | 25\% | 1.60 | 3.50 | 0.82 | 1.80 |
| MAR 800-30 | 10,000 (1,130) | Part Turn | 30 seconds $/ 90^{\circ}$ <br> ( 35 seconds $/ 90^{\circ}$ ) | 25\% | 25\% | 0.34 | 1.20 | 0.15 | 0.75 |
| MAR 800-60 | 10,000 (1,130) | Part Turn | 60 seconds $/ 90^{\circ}$ <br> ( 70 seconds $/ 90^{\circ}$ ) | 25\% | 25\% | 0.34 | 1.20 | 0.15 | 0.75 |
| MAR 1600-70 | 21,000 (2,373) | Part Turn | 70 seconds $/ 90^{\circ}$ <br> ( 80 seconds $/ 90^{\circ}$ ) | 25\% | 25\% | 1.60 | 3.50 | 0.82 | 1.80 |
| MAR 4000-170 | 48,000 (5,424) | Part Turn | 170 seconds $/ 90^{\circ}$ <br> ( 200 seconds $/ 90^{\circ}$ ) | 25\% | 25\% | 1.60 | 3.50 | 0.82 | 1.80 |

NOTE - Multi-turn models are available with the following number of turns: $1.4,5,8,13,18,26$ or 50 . Must be specified when the order is placed.

* (N.L.A.) - No Load Ampere
(L.R.A.) - Locked Rotor Ampere
(1) - Open/Close Service
(2) - Open/Close or Modulating Service


## Duty Cycle

The percentage of time the electric motor is energized vs. the time it is at rest, in reversing duty and with the actuator running at it's rated load maximum published torque.

## Standard Modulating Duty Rating

- 12 motor starts (corrections) per minute
- At the rated duty cycle for that model
- With the speed of operation a minimum of 15 seconds for $90^{\circ}$ or slower
- With positioning accuracy of (+/-) $1 \%$ of total span


## Isolation Relays

To operate multiple actuators in parallel from a single signal requires isolating relays in the field wiring.
Consult factory.
Note - Multi-turn models are available with the following number of turns: $1.4,5,8,13,18,26$ or 50 . Must be specified when the order is placed.

## Spring Return Electric

Optional Manual Override Available


NEMA 4 Enclosure
A.C. Models Only
(Canadian Standard Association)

## CSA NRTL/C Type 4



NEMA 7 Enclosure
A.C. Models Only
(Canadian Standard Association)

| CSA NRTL/C | Class I, Divisions 1 \& 2, <br> Groups C \& D |
| :--- | :--- |
| CSA NRTL/C | Class II, Divisions 1 \& 2, <br> Groups E, F, \& G |
| CSA NRTL/C | Approved to UL Standard No. <br> 429, Electrically Operated Values |

CSA NRTL/C Approved to UL Standard No. 1203, Electrical Equipment for use in Explosion - proof And Dust - Ignition - proof Hazardous (Classified) Locations



SURE 24


SURE 25

## Spring Return Electric

Outline Dimensions (Inches) - SURE 24/25


## Mounting Geometry - Bottom View



## Notes

1. Direction of rotation is based on viewing actuator from top.
2. Drawing shows actuator output shaft in power fail clockwise position.
3. Standard unit fails clockwise (closed).
4. Optional unit fails counter-clockwise (open).
5. NEMA 4 cover shown.

Dimensions given are accurate for NEMA 7.

## Spring Return Electric

Not Available with Manual Override

| NEMA 4/6/7 Enclosure |  | $12 \mathrm{VDC}, 24 \mathrm{VDC}$ |
| :---: | :---: | :---: |
| Approvals |  | Torque Range |
| A.C. Models Only (Canadian Standard Association) |  | 600 pound inches spring end (68 newton meters) |
| CSA NRTL/C | Type 4 and 6 | Speed Range |
| CSA NRTL/C | Class I, Divisions 1 \& 2, Groups C \& D | $5,15 \& 30$ seconds for $90^{\circ}$ revolution, motor operation 2 to 5 seconds spring operation |
| CSA NRTL/C | Class II, Divisions 1 \& 2, Groups E, F \& G |  |
| CSA NRTL/C | Approved to UL Standard No. 429, Electrically Operated Valves | Spring |
|  |  | Helical torsion spring, spring steel XYLAN ${ }^{\circledR}$ coated |
| CSA NRTL/C | Approved to UL Standard No. 1203, Electrical Equipment for use in Explosion - proof And Dust - Ignition - proof Hazardous (Classified) Locations | Standard Features |
|  |  | AC Voltages 4 - SPDT Switches, PTC Heater, Motor Break DC Voltages 2 - SPDT (High Current) Switches, PTC Heater, Motor Break |


| NEMA 4/6/7 Enclosure |  | $12 \mathrm{VDC}, 24 \mathrm{VDC}$ |
| :---: | :---: | :---: |
| Approvals |  | Torque Range |
| A.C. Models Only (Canadian Standard Association) |  | 600 pound inches spring end (68 newton meters) |
| CSA NRTL/C | Type 4 and 6 | Speed Range |
| CSA NRTL/C | Class I, Divisions 1 \& 2, Groups C \& D | $5,15 \& 30$ seconds for $90^{\circ}$ revolution, motor operation 2 to 5 seconds spring operation |
| CSA NRTL/C | Class II, Divisions 1 \& 2, Groups E, F \& G |  |
| CSA NRTL/C | Approved to UL Standard No. 429, Electrically Operated Valves | Spring |
|  |  | Helical torsion spring, spring steel XYLAN ${ }^{\circledR}$ coated |
| CSA NRTL/C | Approved to UL Standard No. 1203, Electrical Equipment for use in Explosion - proof And Dust - Ignition - proof Hazardous (Classified) Locations | Standard Features |
|  |  | AC Voltages 4 - SPDT Switches, PTC Heater, Motor Break DC Voltages 2 - SPDT (High Current) Switches, PTC Heater, Motor Break |



## NEMA 4/6/7 Enclosure

Approvals
A.C. Models Only
(Canadian Standard Association)

CSA NRTL/C Class II, Divisions 1 \& 2, Groups E, F \& G

CSA NRTL/C Approved to UL Standard No. 1203, Electrical Equipment for use in Explosion - proof And Dust - Ignition - proof Hazardous (Classified) Locations

| Models |
| :---: |
| SURE 49 |
| Typical Application |
| For on/off and modulating control of: <br> - Part turn ball, butterfly, plug valves or rotary dampers when emergency shutdown or shutoff capability is required in the event of a loss of power |
| Temperature Range |
| Standard: $\begin{aligned} & -40^{\circ} \mathrm{F} \text { to }+150^{\circ} \mathrm{F} \\ & -40^{\circ} \mathrm{C} \text { to }+65^{\circ} \mathrm{C} \end{aligned}$ <br> Optional: $\begin{aligned} & -60^{\circ} \mathrm{F} \text { to }+150^{\circ} \mathrm{F} \\ & -50^{\circ} \mathrm{C} \text { to }+65^{\circ} \mathrm{C} \end{aligned}$ <br> Optional: Compliance to NFPA 130, capable of operation after exposure to ambient temperature of $482^{\circ} \mathrm{F}\left(250^{\circ} \mathrm{C}\right)$ for a minimum of 1 hour |
| Voltage |
| 115 VAC, 1 Phase, $50 / 60 \mathrm{~Hz}$. 230 VAC, 1 Phase, $50 / 60 \mathrm{~Hz}$. 24 VAC, 1 Phase, 50/60 Hz. 12 VDC, 24 VDC |
| Torque Range |
| 600 pound inches spring end (68 newton meters) |
| Speed Range |
| $5,15 \& 30$ seconds for $90^{\circ}$ revolution, motor operation 2 to 5 seconds spring operation |
| Spring |
| Helical torsion spring, spring steel XYLAN® ${ }^{\circledR}$ coated |
| Standard Features |
| AC Voltages <br> 4 - SPDT Switches, PTC <br> Heater, Motor Break <br> DC Voltages <br> 2 - SPDT (High Current) Switches, PTC Heater, Motor Break |



## Spring Return Electric

Outline Dimensions (Inches) - SURE 49

| Weight |
| :--- |
| NEMA $4 / 6 / 7$ Enclosure: $49 \mathrm{lbs} / 22.2 \mathrm{~kg}$ |



## Mounting Geometry - Bottom View



## Notes

1. Direction of rotation is based on viewing actuator from top.
2. Actuator shown in energized position.
3. It is recommended that the actuator be driven electrically in both directions for normal operartion and prolonged life.

## Spring Return Electric

Optional Manual Override Available


## Spring Return Electric

Outline Dimensions (Inches) - SURE 100

| Weight |
| :--- |
| NEMA 4/6/7 Enclosure: $70 \mathrm{lbs} / 31.8 \mathrm{~kg}$ |



## Conduit Entries

## Conduit Entries



## Notes

1. Direction of rotation is based on viewing actuator from top.
2. Actuator shown in a power fail position.
3. Mounting circle complies with ISO 5211 flange type F07 (except bolt thread). Bolt circle is on center line, not straddling center line.
Two keys are recommended for driving device.
4. It is recommended that the actuator be driven electrically in both directions for normal operartion and prolonged life.

## Spring Return Electric

Optional Manual Override Available


| NEMA 4/6/7 Enclosure |  |
| :--- | :--- |
| Approvals |  |
| A.C. Models Only <br> (Canadian Standard Association) - pending |  |
| CSA NRTL/C | Type |
| CSA NRTL/C | Class I, Divisions $1 \& 2$, Groups <br> C \& D |
| CSA NRTL/C | Class II, Divisions $1 \& 2$, <br> Groups E, F \& G |
| CSA NRTL/C | Approved to UL Standard No. <br> 429, Electrically Operated <br> Valves |
| CSA NRTL/C | Approved to UL Standard No. <br> 1203, Electrical Equipment for <br> use in Explosion - proof <br> And Dust - Ignition - proof <br> Hazardous (Classified) <br> Locations |


| Models |
| :--- |
| SURE 150 |
| Typical Application |
| For on/off and modulating <br> control of: <br> - Part turn ball, butterfly, <br> plug valves or rotary <br> dampers when <br> emergency shutdown <br> or shutoff capability is <br> required in the event of a <br> loss of power |
| Temperature Range |
| Standard: $-40^{\circ} \mathrm{F}$ to $+150^{\circ} \mathrm{F}$ |
| $\quad-40^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ |
| Optional: $\quad-60^{\circ} \mathrm{F}$ to $+150^{\circ} \mathrm{F}$ |
| $\quad-50^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ |

## Spring Return Electric

Outline Dimensions (Inches) - SURE 150


## Conduit Entries

## Conduit Entries



CCW Spring Return


CW Spring Return

## Notes

1. Direction of rotation is based on viewing actuator from top.
2. Actuator shown in a power fail position.
3. Mounting circle complies with ISO 5211 flange type F07 (except bolt thread). Bolt circle is on center line, not straddling center line.

Two keys are recommended for driving device.
5. It is recommended that the actuator be driven electrically in both directions for normal operartion and prolonged life.

## Spring Return Electric

115 \& 230 VAC, 1 Phase, $50 / 60 \mathrm{~Hz}$.

| Model | Output Torque Inch Pounds (N.m) | Electrical Speed of Operation 60 Hz . 50 Hz .) | $\begin{gathered} \text { Speed of Operation } \\ 60 \mathrm{~Hz} .(50 \mathrm{~Hz} .) \end{gathered}$ | Duty Cycle Rating 115 VAC | $\begin{aligned} & \text { Duty Cycle } \\ & \text { Rating } \\ & 220 \text { VAC } \end{aligned}$ | Current Ratings 115 VAC |  | Current Ratings$220 \text { VAC }$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | NLA* | LRA* | NLA* | LRA* |
| Sure 25-5 | 300 (34) | 5 seconds $/ 90^{\circ}$ <br> ( 6 seconds $/ 90^{\circ}$ ) | 2 seconds/90 | $\begin{gathered} 50 \% \\ (1) \end{gathered}$ | $\begin{gathered} 50 \% \\ (1) \end{gathered}$ | 1.40 | 2.15 | CF** | CF** |
| Sure 25-10 | 300 (34) | 10 seconds $/ 90^{\circ}$ <br> (12 seconds/ $90^{\circ}$ ) | 2 seconds/90 ${ }^{\circ}$ | $50 \%$ <br> (2) | $50 \%$ (2) | 1.00 | 1.55 | CF** | CF** |
| Sure 24-10 | 300 (34) | 10 seconds $/ 90^{\circ}$ <br> (12 seconds/90 $)$ | 2 seconds/90 | $\begin{gathered} 25 \% \\ (1) \end{gathered}$ | $\begin{gathered} 25 \% \\ (1) \end{gathered}$ | 0.70 | 1.05 | 0.45 | 65\% |
| Sure 49-5 | 600 (68) | 5 seconds/90 ${ }^{\circ}$ ( 6 seconds $/ 90^{\circ}$ ) | 2 seconds/90 ${ }^{\circ}$ | $\begin{gathered} 25 \% \\ (1) \end{gathered}$ | $\begin{gathered} 25 \% \\ (1) \end{gathered}$ | 1.10 | 1.80 | 1.00 | 1.20 |
| Sure 49-15 | 600 (68) | 15 seconds $/ 90^{\circ}$ (18 seconds/90 ${ }^{\circ}$ ) | 2 seconds/90 ${ }^{\circ}$ | $\begin{gathered} 25 \% \\ \text { (1) } \end{gathered}$ | $\begin{gathered} 25 \% \\ (1) \end{gathered}$ | 0.55 | 1.55 | 0.35 | 0.90 |
| Sure 49-30 | 600 (68) | 30 seconds $/ 90^{\circ}$ <br> $\left(35\right.$ seconds $/ 90^{\circ}$ ) | 2 seconds/90 | $50 \%$ (2) | $\begin{gathered} 50 \% \\ (2) \end{gathered}$ | 0.65 | 0.70 | 0.30 | 0.35 |
| Sure 100-10 | 1,200 (136) | $\begin{gathered} 10 \text { seconds } / 90^{\circ} \\ \left(12 \text { seconds } / 90^{\circ}\right) \end{gathered}$ | $\begin{gathered} 5 \text { seconds } / 90^{\circ} \\ (\text { max })+ \end{gathered}$ | $\begin{gathered} 25 \% \\ (1) \end{gathered}$ | $\begin{gathered} 25 \% \\ (1) \end{gathered}$ | 1.90 | 2.90 | 0.90 | 1.35 |
| Sure 100-30 | 1,200 (136) | $\begin{gathered} 30 \text { seconds } / 90^{\circ} \\ \left(35 \text { seconds } / 90^{\circ}\right. \text { ) } \end{gathered}$ | $\begin{gathered} 7 \text { seconds } / 90^{\circ} \\ (\max )+ \end{gathered}$ | $50 \%$ (2) | $\begin{gathered} 50 \% \\ (2) \end{gathered}$ | 0.65 | 0.95 | 0.35 | 0.45 |
| Sure 150-15 | 1,800 (136) | 15 seconds $/ 90^{\circ}$ <br> (18 seconds/90 ${ }^{\circ}$ ) | $\begin{gathered} 5 \text { seconds } / 90^{\circ} \\ (\max )_{+} \end{gathered}$ | $\begin{aligned} & 25 \% \\ & (1), ~(2) \end{aligned}$ | $\begin{aligned} & 25 \% \\ & (1), ~(2) \end{aligned}$ | 1.90 | 2.90 | 0.90 | 1.35 |

## 24 VAC

| Model | Output Torque Inch Pounds (N.m) | Electrical Speed of Operation 60 Hz . $(50 \mathrm{~Hz}$.) | Speed of Operation 60 Hz . $(50 \mathrm{~Hz}$.) | Duty Cycle Rating 115 VAC | Current Ratings$115 \text { VAC }$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | NLA* | LRA* |
| Sure 49-30 | 600 (68) | 30 seconds $/ 90^{\circ}$ <br> (35 seconds/90 ${ }^{\circ}$ ) | 2 seconds/90 ${ }^{\circ}$ | $\begin{gathered} 25 \% \\ \text { (2) } \end{gathered}$ | 4.50 | 5.00 |

## 12 \& 24 VDC

| Model | Output Torque Inch Pounds (N.m) | Electrical Speed of Operation | Speed of Operation | Duty Cycle Rating 12 VDC | Duty Cycle Rating 24 VDC | Current Ratings 12 VDC |  | Current Ratings 24 VDC |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | NLA* | LRA* | NLA* | LRA* |
| Sure 49-5 | 600 (68) | 5 seconds/90 ${ }^{\circ}$ | 2 seconds/90 <br> (1) | $\begin{gathered} 50 \% \\ \text { (1) } \end{gathered}$ | 50\% | 1.00 | 22.00 | 1.00 | 12.30 |
| * (N.L.A.) - No Load Ampere <br> ** (CF) - Consult Factory |  | (L.R.A.) - Locked Rotor Ampere(1) - Open/Close Se + - Approximate, Based on Load |  |  | (2) - Open/Close or Modulating Service |  |  |  |  |

## Limit Switches (Sure 24 \& 25)

Standard: Two-single pole, double throw type (SPDT) with an option for 2 or 4 additional.
Ratings: UL and CSA listed. MIL-PRF-8805 Qualified Listing 25 amp at $277 \mathrm{VAC} ; 1$ H.P. at 125 VAC; 2 H.P. at 250 VAC

## Isolation Relays

To operate multiple actuators in parallel from a single signal requires isolating relays in the field wiring. Consult factory.

Limit Switches (Sure 49, 1007 150)
Standard: Four-single pole, double throw type (SPDT) with an option for 2 additional.
Ratings: Ratings: UL and CSA listed.
$15 \mathrm{amp} \& 1 / 2$ H.P. at 125 or 250 VAC
$1 / 2 \mathrm{amp}$ at 125 VDC; $1 / 4 \mathrm{amp}$ at 250 VDC
Lamp Load: 5 amp at 120 VAC
Optional: All double pole, double throw type (DPDT).
Ratings: Ratings: UL and CSA listed. 10 amp at 125 or 250 VAC (form ZZ) 1/2 H.P. at 125 VDC; $3 / 4$ H.P. at 250 VDC

## Heater

PTC (Positive Temperature Coefficient) Heater standard in an AC Voltage Models

## Duty Cycle

The percentage of time the electric motor is energized vs. the time it is at rest, in reversing duty and with the actuator running at it's rated load-maximum published torque.

## Standard Modulating Duty Rating

- 12 motor starts (corrections) per minute.
- At the rated duty cycle for that model.
- With the speed of operation a minimum of 15 seconds for $90^{\circ}$ or slower.
- With positioning accuracy of (+/-) $1 \%$ of total span.


## D.C. Analog - EASC SCC-05



## Application

The SCC-05 EASC (Electric Actuator Smart Controller) card is a costeffective means for accurate and precise positioning control of RCS actuators utilizing an analog input signal. The EASC "One-Switch" setup system eliminates the need for external meters, dip switches, trimming potentiometers, or a display screen on the module. Simply set the full open and full closed positions, and the microprocessor technology does the rest. For control applications requiring an input-only control requirement, the SCC-05 provides excellent performance and a variety of standard features suitable for today's challenging automation and control requirements.

## Features

Mounts internally in RCS actuator models: MAR-10, MAR-50, MAR-90, MAR-100, MAR-160, MAR-250, MAR-800 \& all SurePowr models.

- Simple single switch setup allows complete control of controller configuration
- One step selection of input/output ranges including 4-20 mAdc, 1-5 $\mathrm{Vdc}, 2-10 \mathrm{Vdc}$ and $0-10 \mathrm{Vdc}$, or virtually any custom range required
- "Learns while it runs" tuning makes configuration simple
- Selectable fail options
- Intelligent positioning reduces motor cycling, increases motor life and extends the actuator duty
- Optional Modbus RTU remote control over a RS-485 network. Complete access to all controller functions from your factory automation system
- Quick disconnect terminal strips facilitate fast and easy actuator maintenance and troubleshooting
- Always wires the same; no need to determine rotation direction during installation; rotation is selected at setup
- Robust power switching components, designed specifically for actuator motors, virtually eliminate field failures


## Specifications

## Power Requirements

Model SCC05-115/230 A:
Single phase, 115 or $230 \mathrm{VAC} 50 / 60 \mathrm{~Hz}$. (Jumper selectable)
Input Command Signal
Menu selectable factory defaults:

- 4-20 mADC
- 1-5 VDC
- 2-10 VDC
- 0-10 VDC

Infinite adjustment during System
Signal Impedance
Input: $250 \Omega$ current, $200 \mathrm{~K} \Omega$ voltage

## Power Output

Solid state, isolated from the input command signal and rated at:

- 5 amps continuous at 115 VAC
- 5 amps continuous at 230 VAC

All ratings assume the EASC is mounted on the actuator base plate

## Sensitivity

Full scale sensitivity adjustable from 0\% to 9\%
Dead Band
Automatic deadband system with manual override.

## Zero Span Adjustment

Simple setup, just set the fully closed position and fully open positions and input calibration is automatically adjusted.

## Split Range

Settable within the span range using at least 1.5 VDC or 3 mA of input.

## Remote Control

Optional Modus RTU control of all controller functions over a RS-485 multi-drop network

## Ambient Temperature

$-40^{\circ} \mathrm{F}$ (with heater) to $+150^{\circ} \mathrm{F}\left(-40^{\circ} \mathrm{C}\right.$ to $\left.+65^{\circ} \mathrm{C}\right)$

## Action on Loss of Command Signal

Factory default:

- Fail in last position (no movement)
- For a setting of ZERO input signal, the system fails to minimum signal position
Additional settings available at setup:
- Fail open (maximum signal value)
- Fail closed (minimum signal value)
- Fail to a preset position

Size
$3.5 \times 1.63 \times 4$ in.

## D.C. Analog - EASC SCC-10



## EASC (Micro-Processor Based Analog Controller)

The Electric Actuator Smart Controller (EASC SCC-10) card provides accurate positioning control of electric motor actuators using an analog input signal. Setup and calibration is greatly simplified using microprocessor based technology. There are no dip switches to set or trim pots to adjust. Setup is quick and easy using the EASC menu viewed on an LED display. No external meters are required, even for potentiometer setup. Once the initial menu settings are chosen, the EASC performs a self-calibration routine, applying the menu selections to actual actuator performance. Calibration values are then stored in permanent non-volatile memory.

## Profibus D.P.



| Model |
| :--- |
| DPC-100 |
| 12 or 24 Volt D.C. Actuators |


| Model |
| :--- |
| DPC-120 |
| 115 Volt A.C. Actuators |

## Features

- Two wire control reduces installation and start up time compared to multi-cable wiring
- Automatic calibration cuts down on start up time
- No deadband eliminates need for field adjustment.
- On line configuration of 36 operational parameters using generic Profibus software
- Low power consumption; does not require ventilation
- Electronic overload protection with built-in current monitoring
- LED indicators for input, outputs and communication channel
- Automatic calibration with local pushbutton or remote command
- Dynamic breaking eliminates overshooting
- Robust power switching components, designed specifically for actuator motors, virtually eliminates field failures


## Specifications

## Power Supply

DPC-100: 24/12 VDC
DPC-120: 120 VAC

## Communication Interface

Profibus Standard

## Protocol

Profibus DP (Distributed Process)

## Feedback

Potentiometer 1000 Ohms/Optical Encoder

## Position Input Accuracy

1.0\% full scale standard, Maximum 0.1\%

## Temperature

$-40^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}\left(-40^{\circ} \mathrm{F}\right.$ to $\left.+158^{\circ} \mathrm{F}\right)$

## Relative Humidity

0 to 90\% non-condensing

## Dimensions

DPC-100: $4.0 \times 1.5 \times 2.5 \mathrm{in}$. DPC-120: $4.25 \times 1.75 \times 3.75$ in.
The DPC-100 \& DPC-120 provide the following status and fault signals:
Valve full closed
Valve full open
Percentage of open
Valve seeking position
Motor running
Valve closing
Valve opening
Motor thermostat tripped
Incomplete travel
Valve opening or closing manually
Valve jammed/current limiting
Motor still energized after stop or end of travel
Controller self-test (detects problems)
Communication failure
Average running current load
Peak running current load
Idle current load

## Devicenet ${ }^{\text {m }}$



## Application

For on/off or positioning control of motorized valves. DeviceNet" is a type of communication network that allows up to 63 field devices to be linked together with a singe five-conductor cable. DeviceNet" is a product of Allen-Bradley and is an open, non-proprietary, bus network. Typically, a DeviceNet ${ }^{\text {t" }}$ system is used with the Allen-Bradley PLC5 and SLC series of programmable logic controllers. A standard DeviceNet ${ }^{\text {m' }}$ Scanner interface is available for both types. Devices in the field are connected via a drop line to a 5 conductor trunk-line that is then routed to the scanner card.

## Features

- Provides open/stop/close or positioning control with limit switch status feedback
- Provides instantaneous motor reversal protection
- Command and end-of-travel verification alarm
- Conforms to ODVA standard
- Easy-to-see LED indicators for all control outputs, status inputs and diagnostic alarm
- ESD functions for 'go open', 'stay put', or 'go closed'


## Specifications

Hardware Specifications
Supply Power: 2W @ 24VDC
Operating Temperature: $-20^{\circ} \mathrm{C}-70^{\circ} \mathrm{C}$
Storage Temperature: $-40^{\circ} \mathrm{C}-80^{\circ} \mathrm{C}$
Humidity: $90 \%$ Non Condensing
Solid State Outputs: (2) Isolated 600VAC 15A
Digital Inputs: (8) Dry Contacts
Analog Inputs: (2) Channels (see below)
Processor: Temic 89C51CC01
RAM: 1K
Flash: 32K
EEPROM: 32 K
Serious Interfaces
One CAN 2.0 port.
Network Communication Protocols
Module Supports DeviceNet ${ }^{\text {t" }}$ Group 2 Slave.
Analog Inputs Specification
Resolution: 10bit
Accuracy: $1 \%$ of FS .
Linearity: $1 \%$ of FS .
Temperature Drift: 2\% of FS.
Range: 0 to 5 V or $0-20 \mathrm{~mA}$ input for Al1
$1-5 \mathrm{~K}$ Potentiometer for the Position Feedback.

Technical Summary of DeviceNet ${ }^{\text {m" }}$
Network Size: Up to 64 nodes (including scanner)
Network Length: Up to 1,640 ft. at 125 Kbps .
Data Packets: 0-8 bytes
Bus Topology: Trunkline/Dropline
Cable: 5-Conductor cable (2 for power, 2 for communication, and 1 for ground).
Thick Trunk Lines: Belden 3082A or 3083A
Thin Drop Lines: Belden 3084A or 3085A
Drop Lines: Max. drop length is 20 ft . with
cumulative drop length of 512 ft .
Repeaters: Not currently, but expected in future revisions of specifications.
Input/Output Listing
Digital Input Status:
Bit 0 Communication Loss
Bit 1 Reserved
Bit 2 Loss of Position Signal
Bit 3 Motor Stall
Bit 4 Limit Calibration Incorrect
Bit 5 Thermostat Trip
Bit 6 Manual Operation
Bit 7-15 Reserved
Cumulative drop length of 512 ft .
-

Environmental Temperature Range:
Storage: $-40^{\circ} \mathrm{C}$ to $+90^{\circ} \mathrm{C}$ Operating: $-20^{\circ} \mathrm{C}$ to $+80^{\circ} \mathrm{C}$
Humidity Range:
$5 \%$ to $95 \%$ at $25^{\circ} \mathrm{C}$
non-condensing

## Vibration:

IEC 6B-2-6 1G @ 40-50 Hz., $0.012 \mathrm{p}-\mathrm{p}$ @ 10-40 Hz.

## Modbus



## Features

- High resolution position input for up to $0.1 \%$ accuracy
- 4-120/240VAC inputs for open and closed limit switches and 2 general purpose inputs
- Simple 4 -wire Modbus-485 communication network includes supervisory power
- Robust communication, up to 500 m cable length
- Plugable terminal strips for easy field installation
- Direct mounting within the actuator
- Low power consumption; does not require ventilation
- Electronic overload protection with built-in current monitoring optional
- High power outputs can directly drive small motors
- LED indicators on inputs, outputs and communication channel
- Automatic calibration using local push button or remote command
- Multi-vendor PLC support through the standard Modbus communication module


## Typical Applications

- Blending of bulk materials
- Petroleum products and other liquids flow control
- Level control for maintaining process supply


## Application

The Modbus is an application specific controller, designed for positioning electric actuators using rotary feedback. Typical devices include rotary and linear actuators. Feedback may be via a potentiometer or a quadrature optical encoder. Controller outputs can drive small electric motors or motor starters directly.
A Modbus-485 communication network allows up to 100 devices on a single channel. The Modbus is powered by 24VDC and provides four supervisory inputs, configurable as limit switches or force open/close signals.
Automatic calibration is provided which requires no loop tuning. All operating parameters can be set as registers in the Modbus communications map.

## Specifications

## Actuator

| Voltage | 120/240VAC 1ø |
| :--- | :--- |
| Current | 4A (2 minute $25 \%$ duty-cycle) |
| Fuse | GMA 4 replaceable |

## Supervisory

Voltage 10 to 25VDC
Current 30 mA @ 24VDC

## Auxiliary Inputs

Voltage 120/240VAC
Current $\min 10 \mathrm{~mA} / \mathrm{max} 20 \mathrm{~mA}$

## Communication

Standard Modbus-RS485 differential
Distance $500 \mathrm{~m}(1,640 \mathrm{ft}$.)
Input Load 12 K ohm, standard
Termination $120 \Omega$ balanced line
Position
Resolution 12 bit (1 part in 4096)
Accuracy $0.1 \%$ full scale
Potentiometer $1000 \Omega$ typical ( 500 to $10 \mathrm{k} \Omega$ )
Quadrature
Optical Encoder 1000 to 4096 pulses

## Environment

Temperature $-40^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}\left(-40^{\circ} \mathrm{F}\right.$ to $\left.+158^{\circ} \mathrm{F}\right)$
Relative Humidity 0 to $95 \%$ non-condensing
Dimensions
Length $\quad 96 \mathrm{~mm}(3.75 \mathrm{in})$
Width $\quad 70 \mathrm{~mm}(2.75 \mathrm{in})$
Height $\quad 36 \mathrm{~mm}(1.40 \mathrm{in})$


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